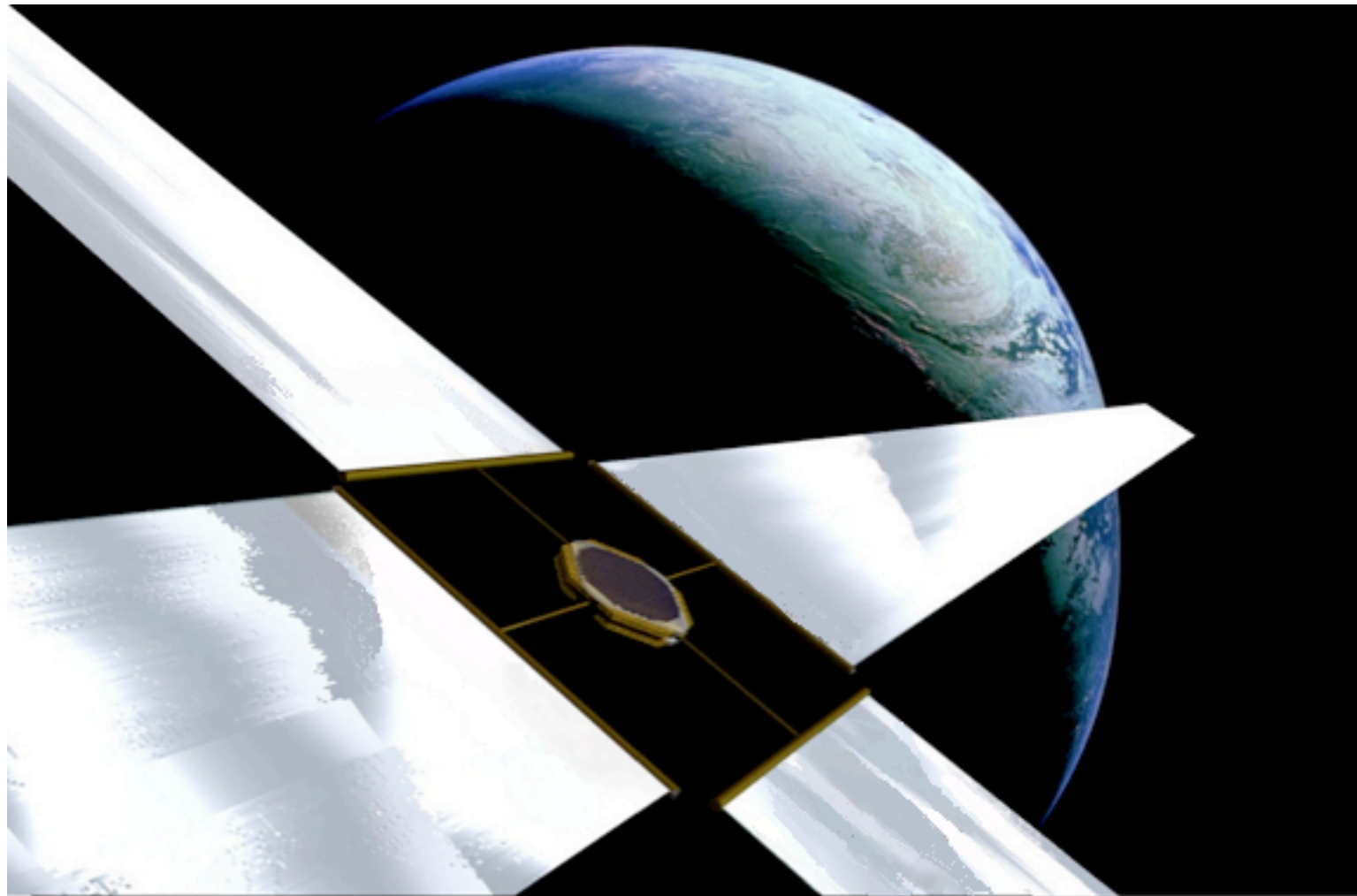


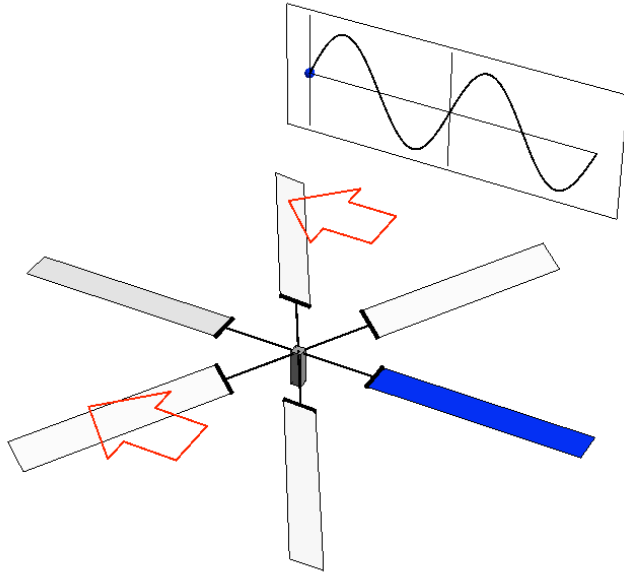
# Solar Cube Heliogyro Cubesat



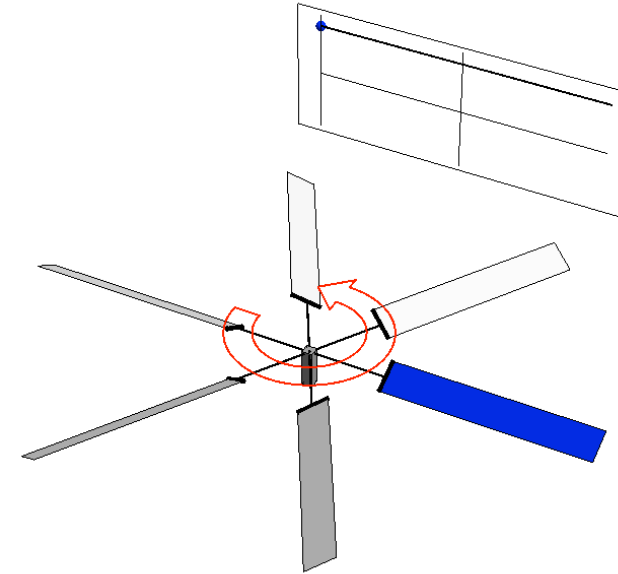
Opening Solar System Exploration to the Masses

Richard S. Blomquist, PhD

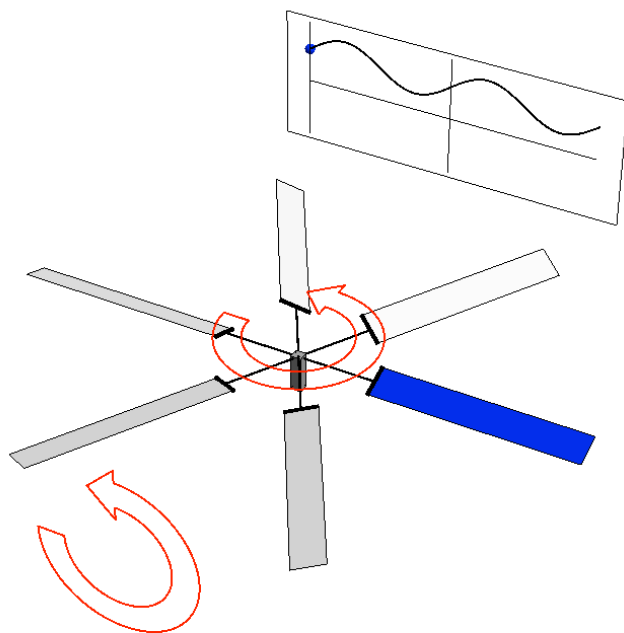
# Pitch Maneuvers



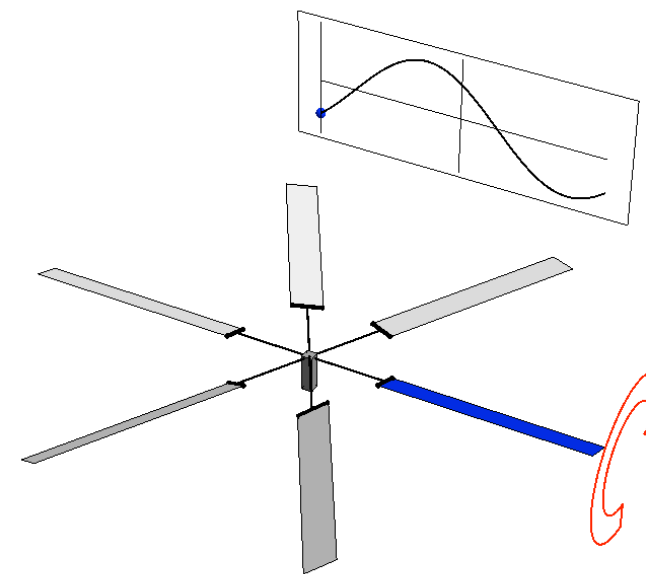
Cyclic



Collective

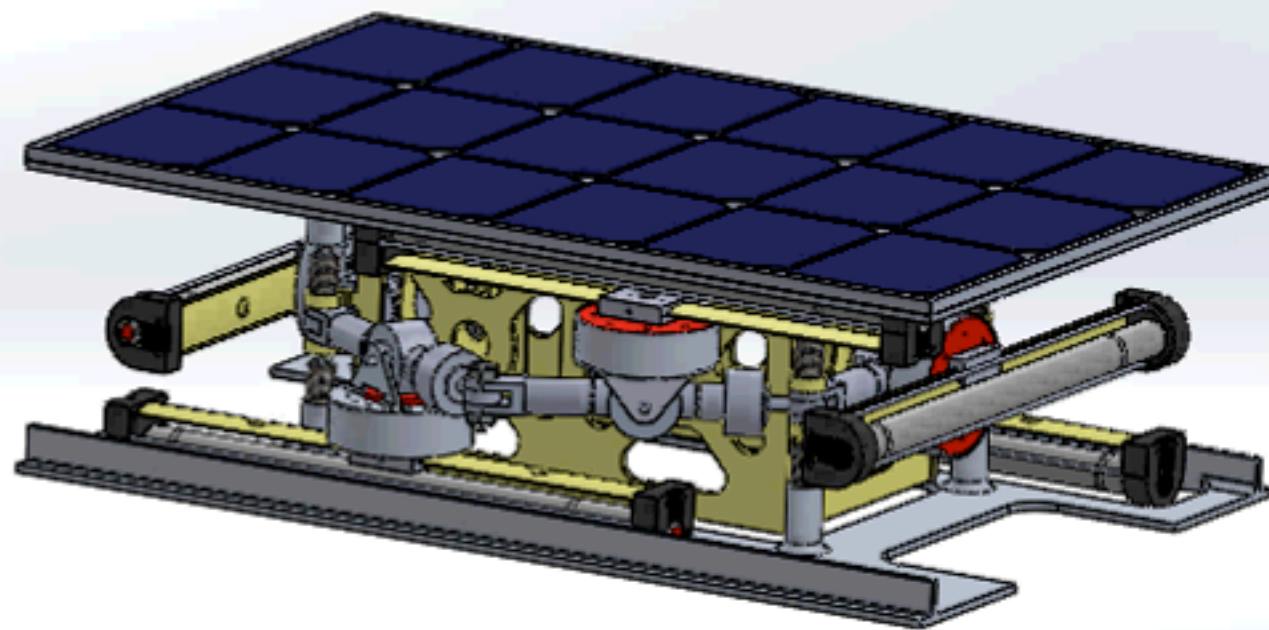


Collective-cyclic



Half-P

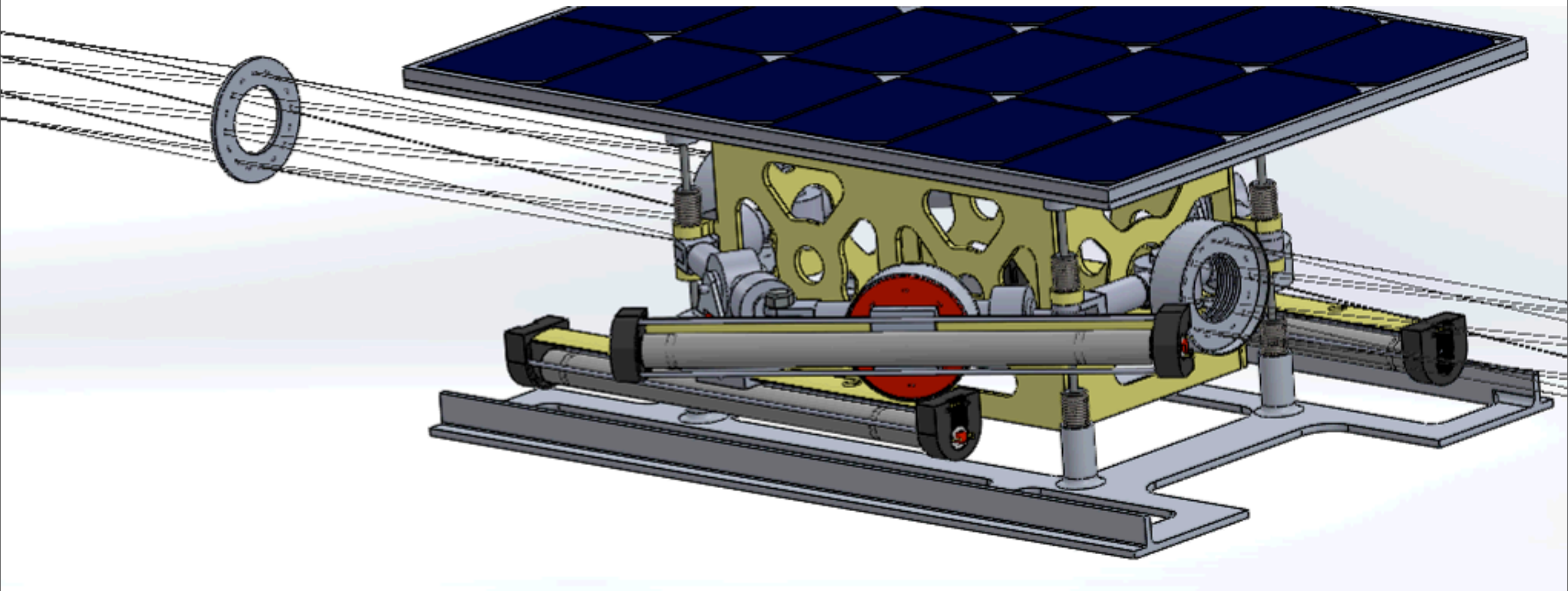
# Solar Cube



- 6U Form Factor
- 6 Blades, 0.2m x 3μ x 200 m
- Charact. Accel = 0.22 mm/s<sup>2</sup>
- Expanding Chassis

- Articulating Booms
- 2U Avionics/Payload
- Total Weight < 10 kg.

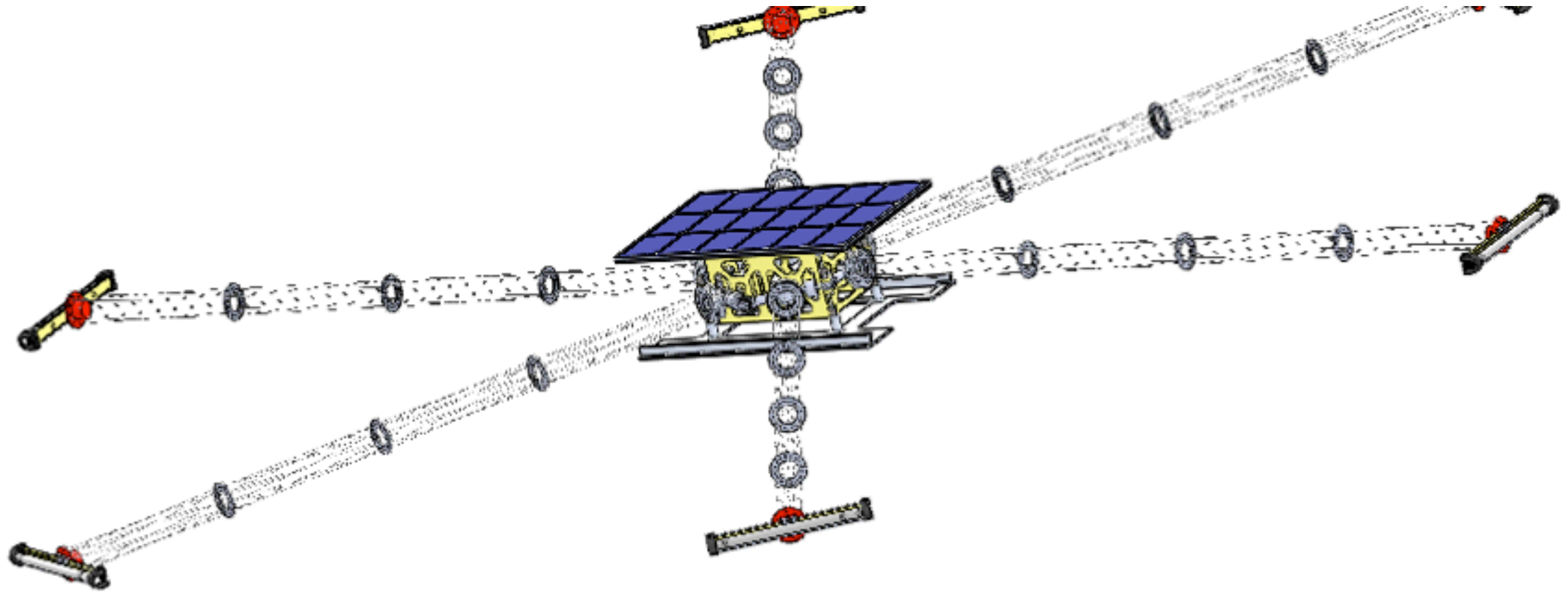
# Solar Cube Deployment



- 6U Form Factor
- 6 Blades,  $0.2\text{m} \times 3\mu \times 200\text{ m}$
- Charact. Accel =  $0.22\text{ mm/s}^2$
- Expanding Chassis

- Articulating Booms
- 2U Avionics/Payload
- Total Weight < 10 kg.

# Solar Cube Deployment

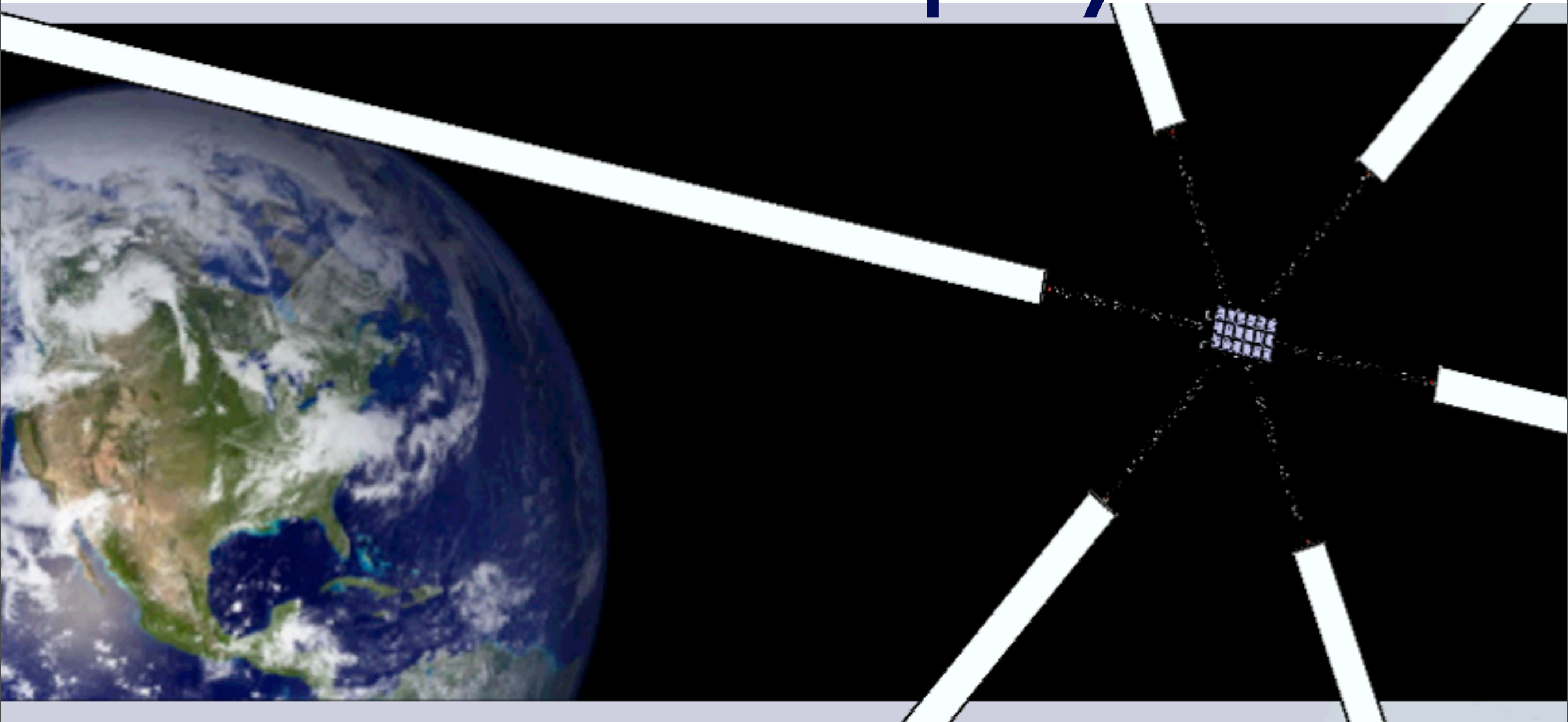


- 6U Form Factor
- 6 Blades,  $0.2\text{m} \times 3\mu \times 200\text{ m}$
- Charact. Accel =  $0.22\text{ mm/s}^2$
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# Solar Cube Deployment



- 6U Form Factor
- 6 Blades,  $0.2\text{m} \times 3\mu \times 200\text{ m}$
- Charact. Accel =  $0.22\text{ mm/s}^2$
- Expanding Chassis

- Articulating Booms
- 2U Avionics/Payload
- Total Weight < 10 kg.



# What Does a 1000:1 Aspect Ratio Look Like?

Assume a 1 meter wide blade



10:1



100:1



1000:1

Why can a 1000:1 ratio blade be controlled?

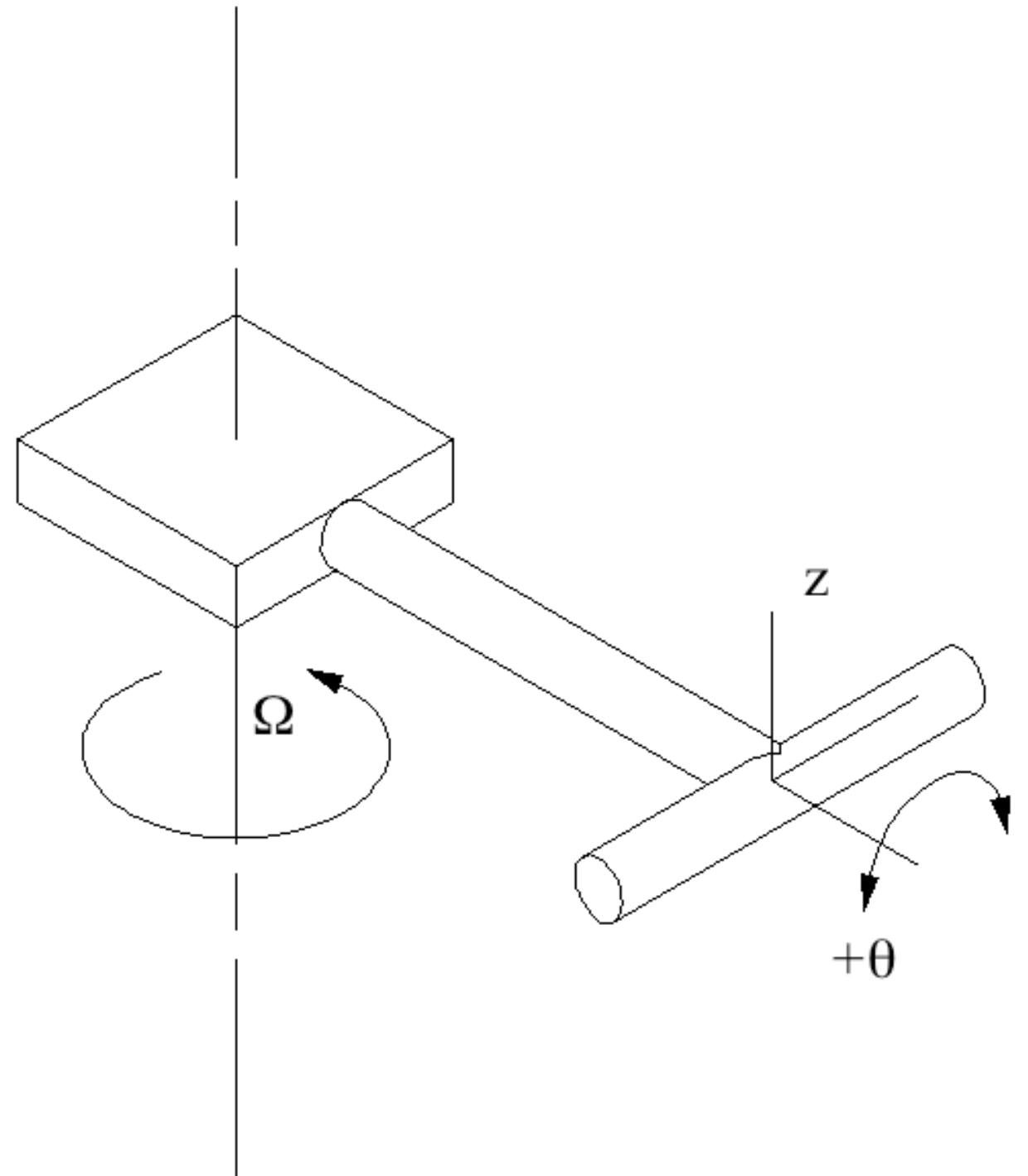
# Fundamental Principle

Bar, hinged at its center,  
rotating about a vertical axis

Governing Equation

$$\ddot{\theta} + \frac{1}{2}c \sin 2\theta = 0$$

$$c = \frac{(I_z - I_y)}{I_x} \Omega^2.$$





# Fundamental Principle

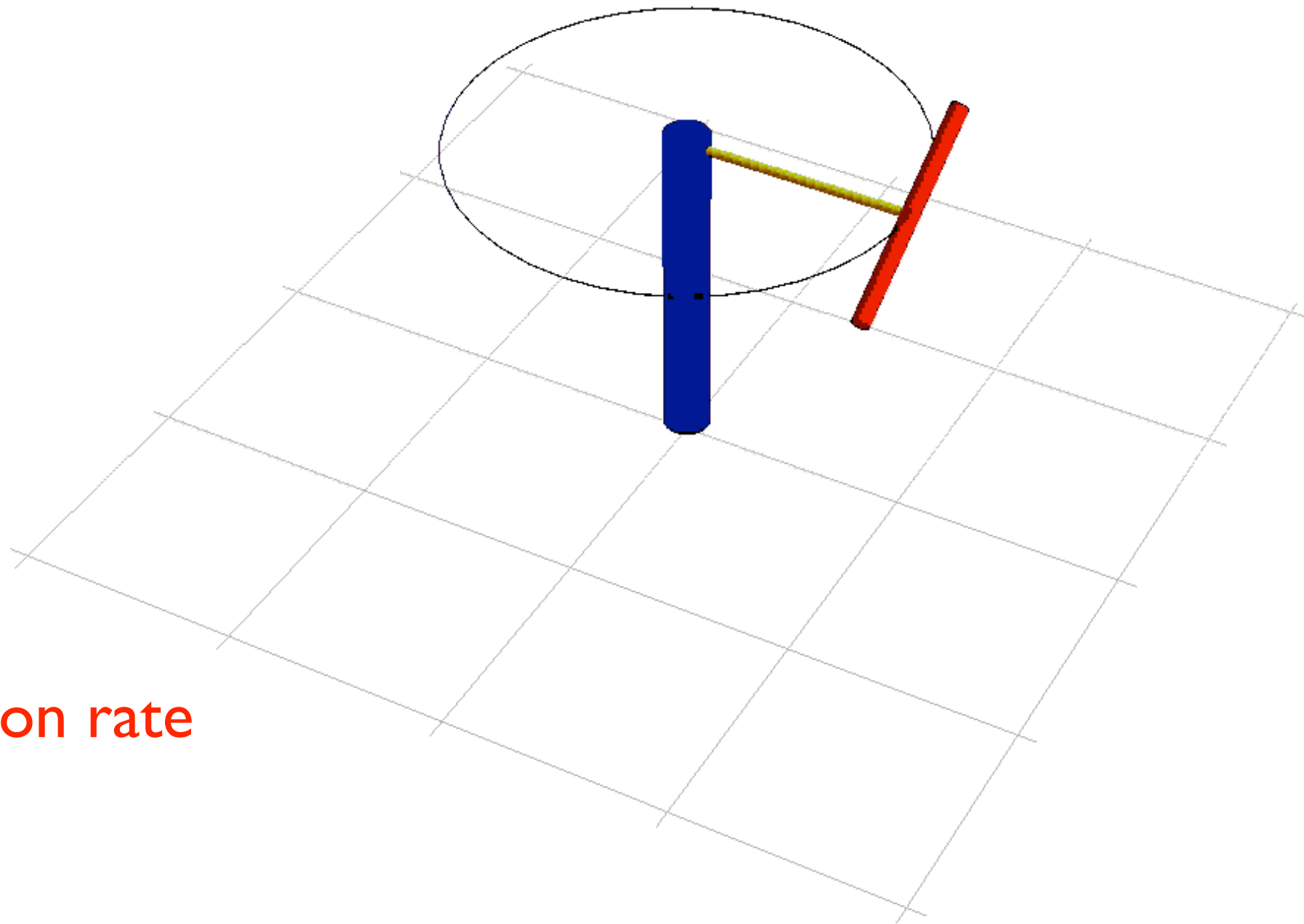
Bar, hinged at its center,  
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Governing Equation

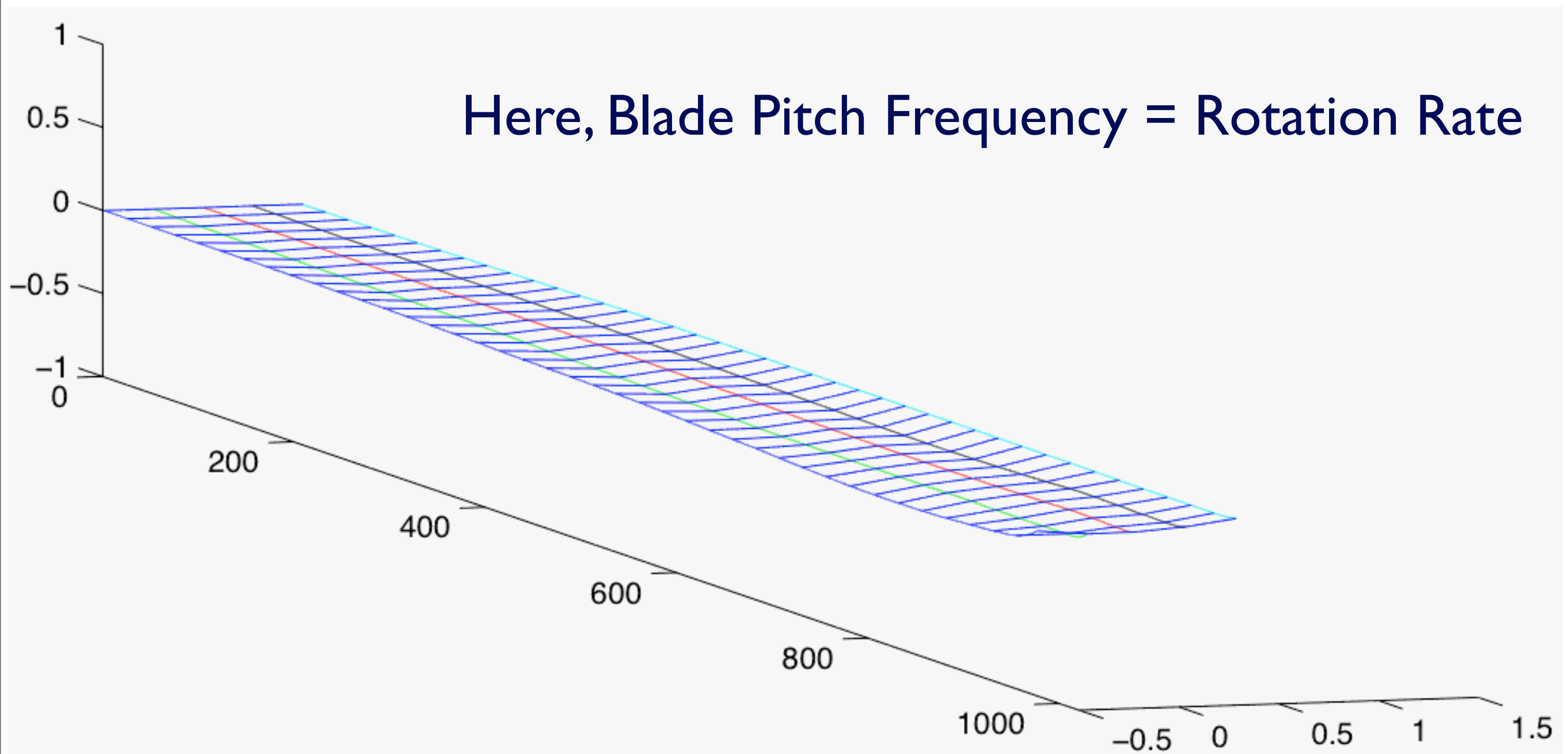
$$\ddot{\theta} + \frac{1}{2}c \sin 2\theta = 0$$

$$c = \frac{(I_z - I_y)}{I_x} \Omega^2.$$

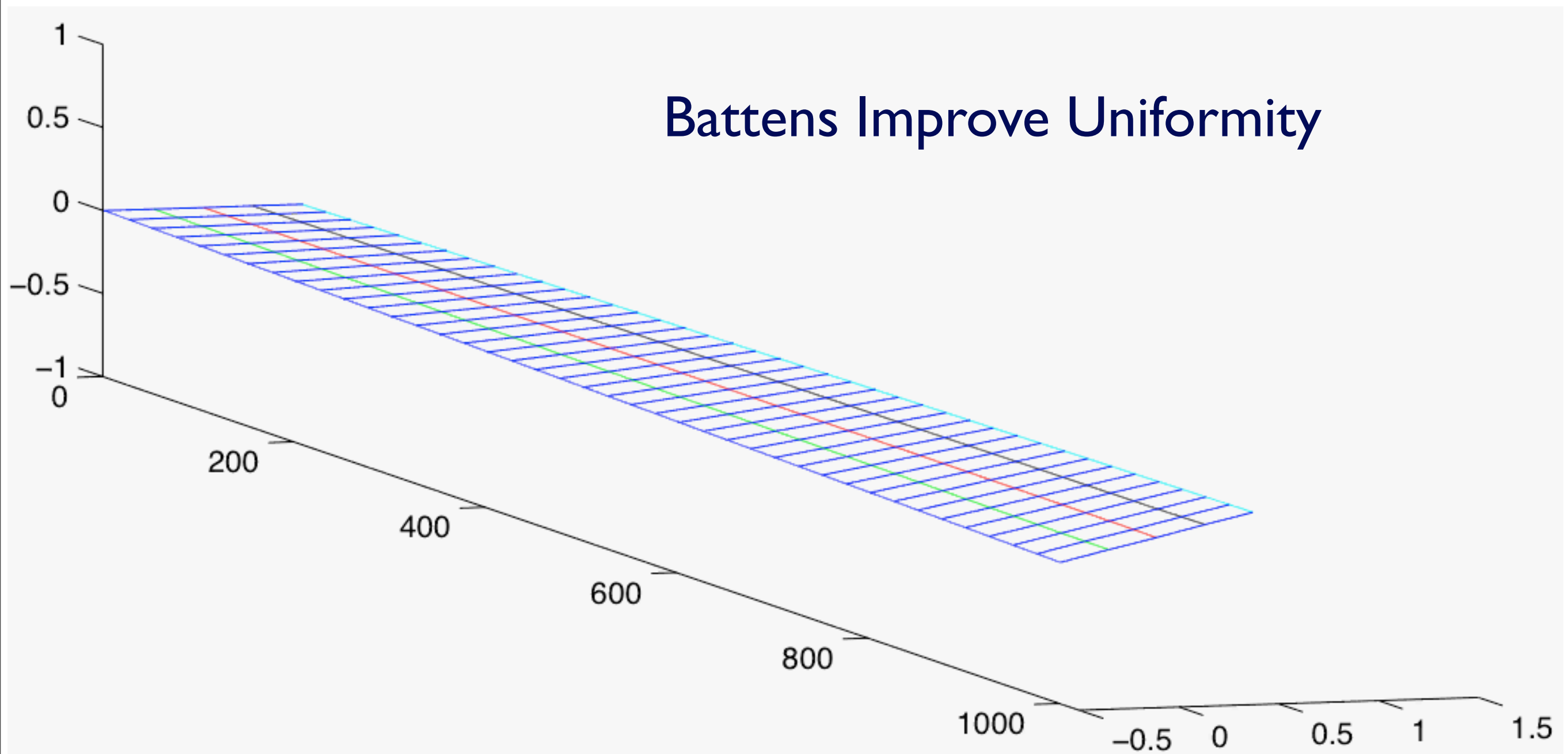
Pitch frequency  $\sim$  rotation rate



# 1000:1 BLADE BEHAVIOR: NO BATTENS



# 1000:1 BLADE BEHAVIOR: BATTENS



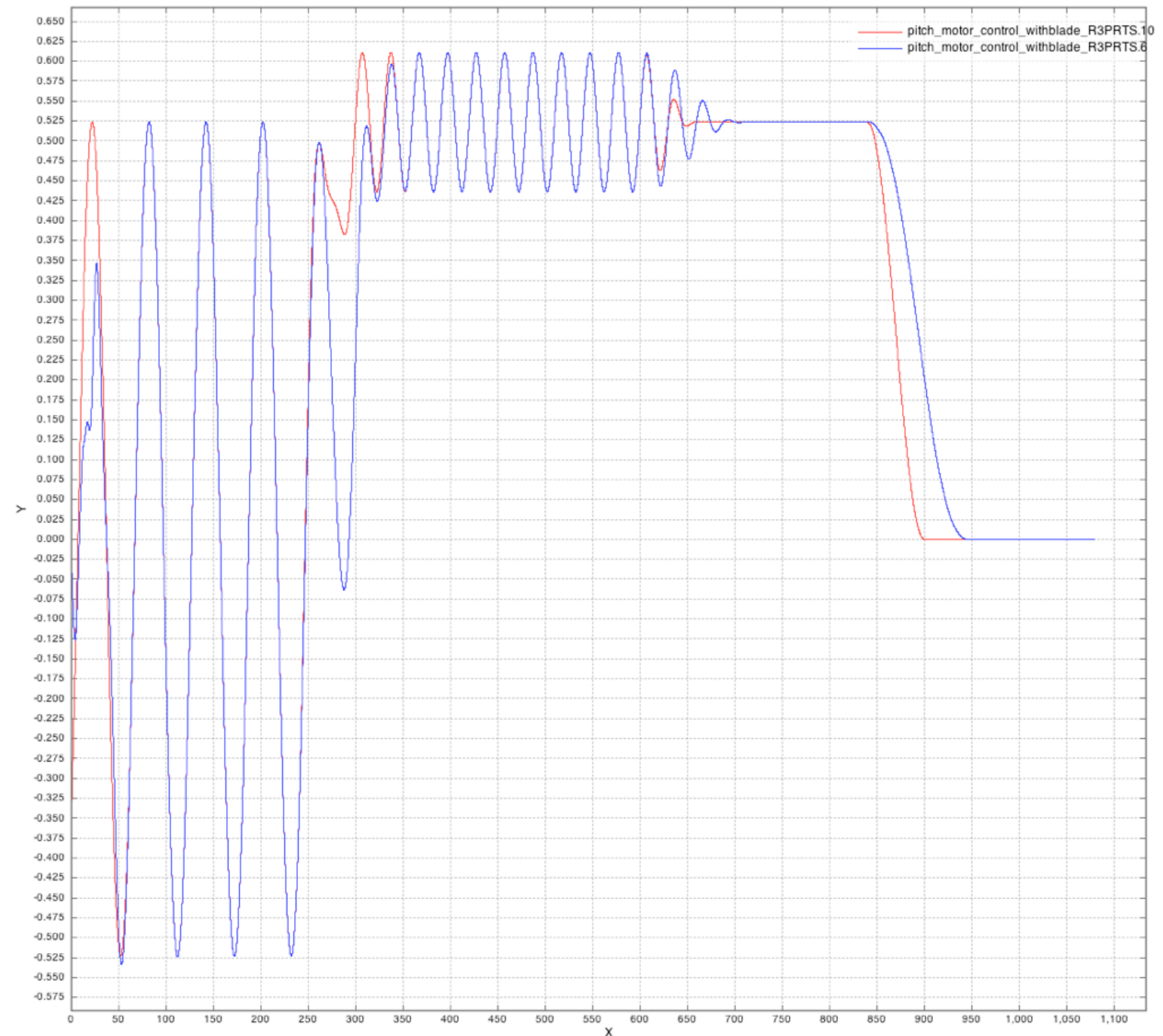


# Pitch Actuation Control

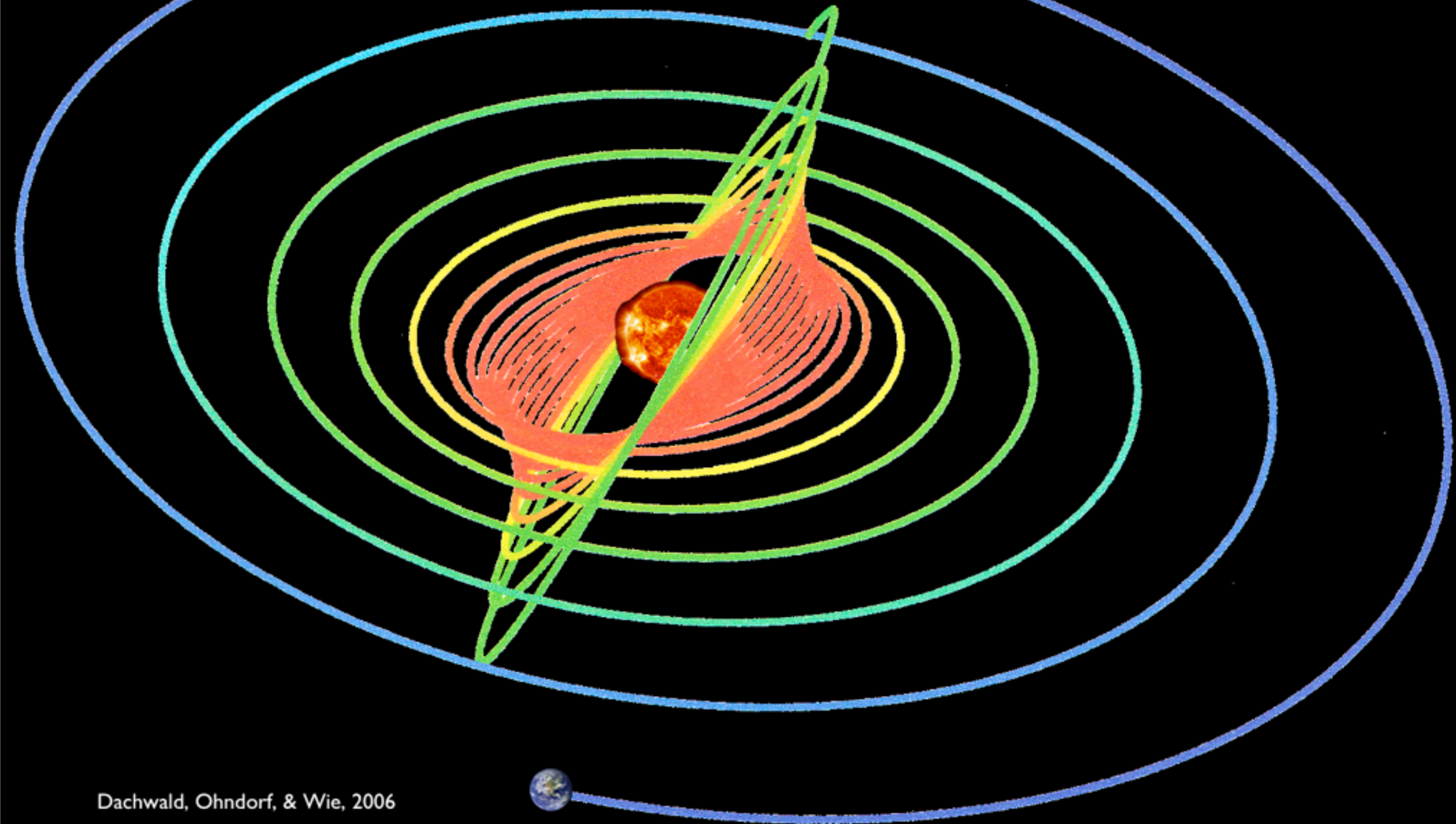
Pitch control of highly flexible blade is possible

**Red** is reference signal  
**Blue** is blade root pitch

Pitch vs. Time



# Solar Polar Imager



Dachwald, Ohndorf, & Wie, 2006

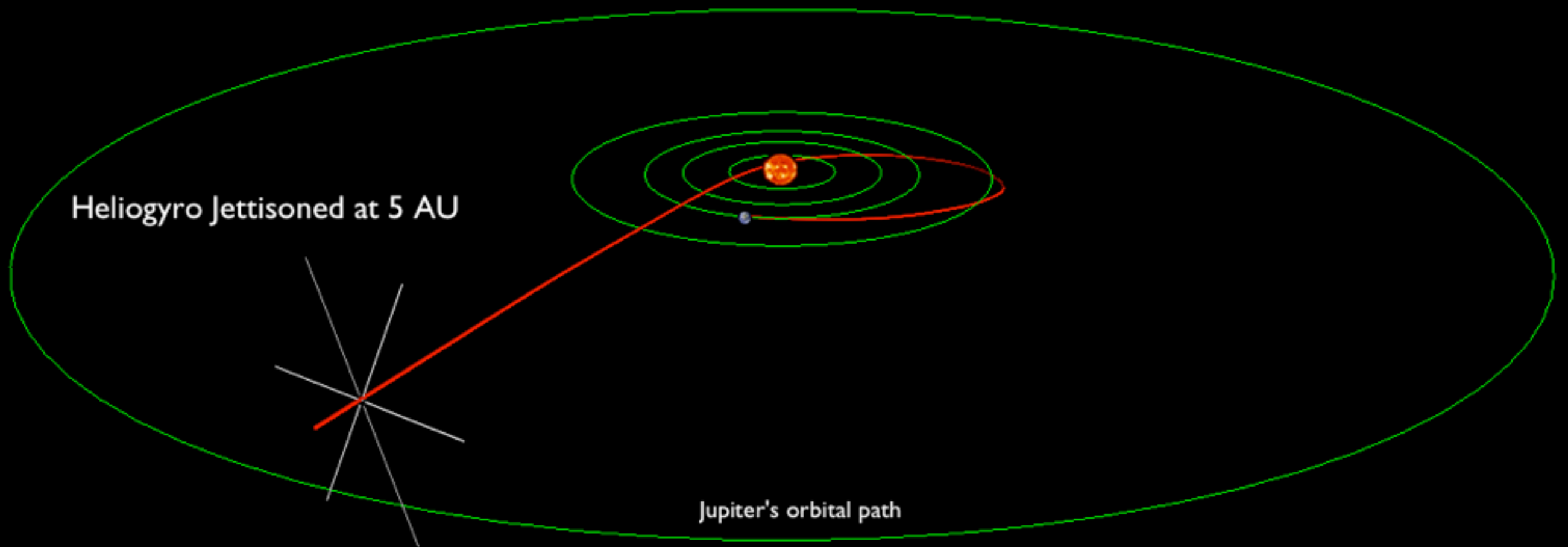
AIAA/AAS Astrodynamics Specialist Conference, 21-24 August 2006

# Sub-L1 Lagrange Point





# Dash to Heliopause



Based on Sauer'99

<http://trs-new.jpl.nasa.gov/dspace/handle/2014/16979>

# Heliogyro Configurations for Big 3

	Sun-Earth LI	Solar Polar	Interstellar Heliosphere
Blades	12	12	24
Chord, m	2	2	2
Blade Length, m	415	960	2,000
Aspect Ratio	208	480	1,000
Blade Thickness, $\mu\text{m}$	3.00	3.00	0.67
Rotational Period, s	30	480	120
Sail S/S Mass, kg	45	101	96
Non-sail Mass, kg	251	300	150
Total S/C mass, kg	296	401	246
Areal Density, $\text{g/m}^2$	4.5	4.38	1.00
Charact. Accel, $\text{mm/s}^2$	0.246	0.419	2.85
Precess rate, $^\circ/\text{day}$	15.3	105.5	56.7

# Applications for Nanosat Community

- A gravitational offset of the sun, a planet, or a moon to allow a persistent presence;
- Decreased transit time for very long trajectories (larger  $\Delta V$ );
- A substitute for a booster to the moon and beyond;
- Increased flexibility of launch opportunities -- orbital insertion needn't be where the final orbit is, due to the ability to accomplish orbital altitude, phase, and plane changes;
- Rapid spacecraft deorbiting;
- Repeated repositioning capability.

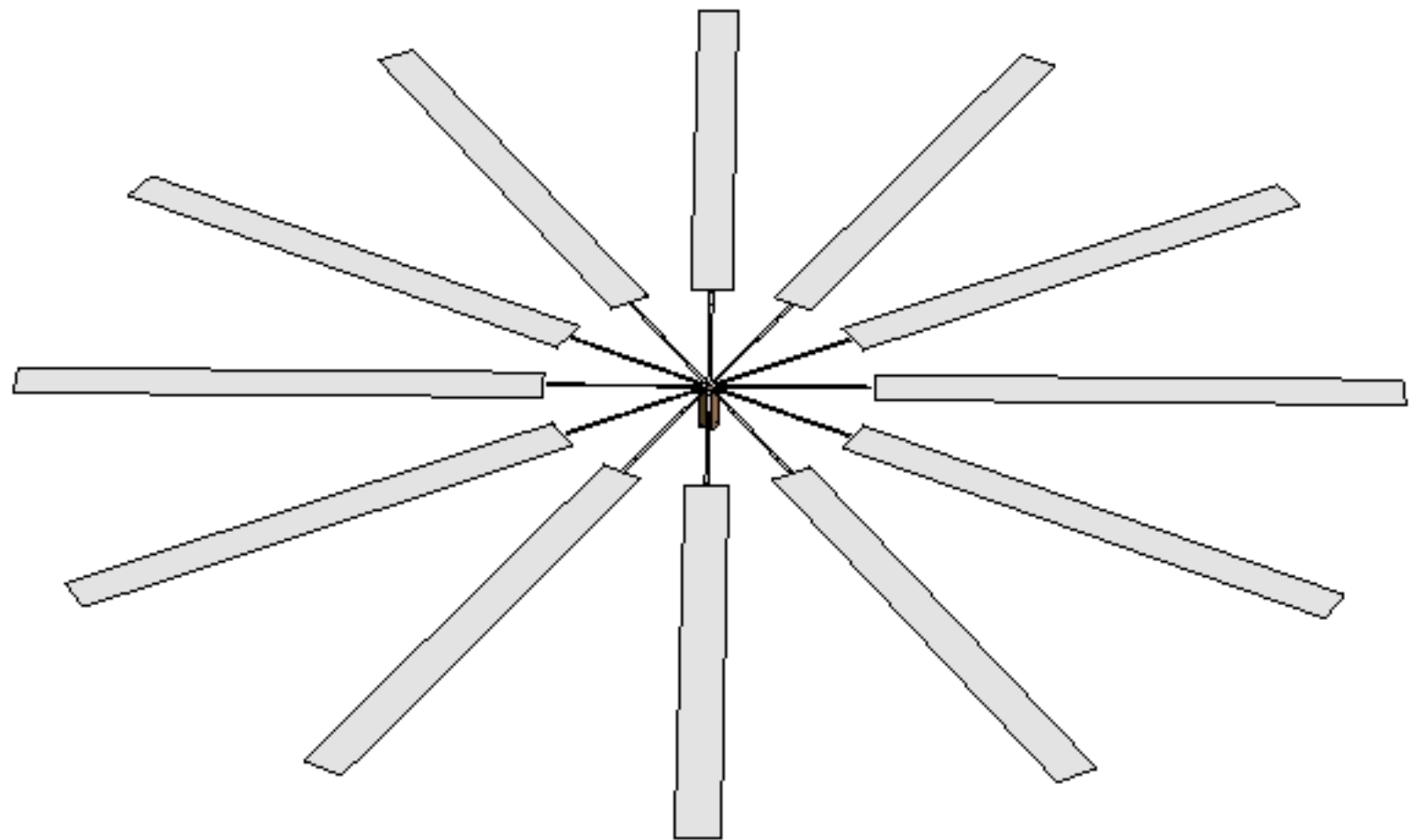


# What Performance Can a Cubesat Heliogyro Provide?

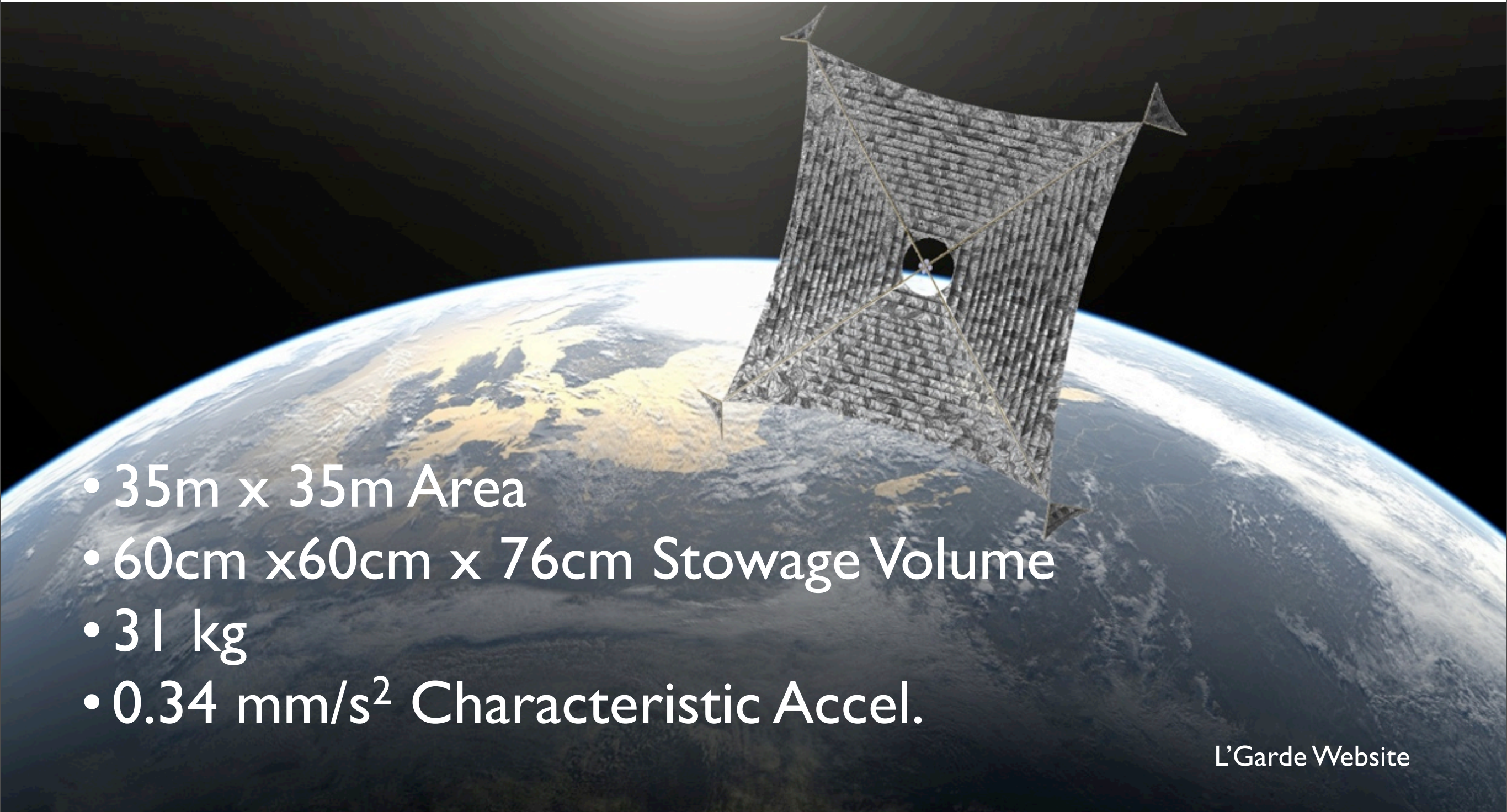
- Assume a 12U form factor
- Scale up to 12 blades
- Each blade 0.32m x 320m x 3 $\mu$
- 2.5U Avionics/payload envelope
- 16 kg
- **0.7 mm/s<sup>2</sup> Characteristic Accel.**
  - Sub-L1 0.246 mm/s<sup>2</sup>
  - • Solar Polar 0.419 mm/s<sup>2</sup>
  - Heliopause 2.85 mm/s<sup>2</sup>

If blades were 1 $\mu$  thick,  
Characteristic Accel = 1 mm/s<sup>2</sup>

How does this compare with  
Sunjammer?



# Compare to Sunjammer

- 
- A solar sail spacecraft is shown in orbit above the Earth's horizon. The sail is a large, rectangular, woven mesh structure, currently folded into a compact, diamond-like shape. It is held together by a central hub and four corner struts. The Earth's blue and white horizon curves across the lower half of the image, with some landmasses visible. The background is the blackness of space.
- 35m x 35m Area
  - 60cm x 60cm x 76cm Stowage Volume
  - 31 kg
  - 0.34 mm/s<sup>2</sup> Characteristic Accel.

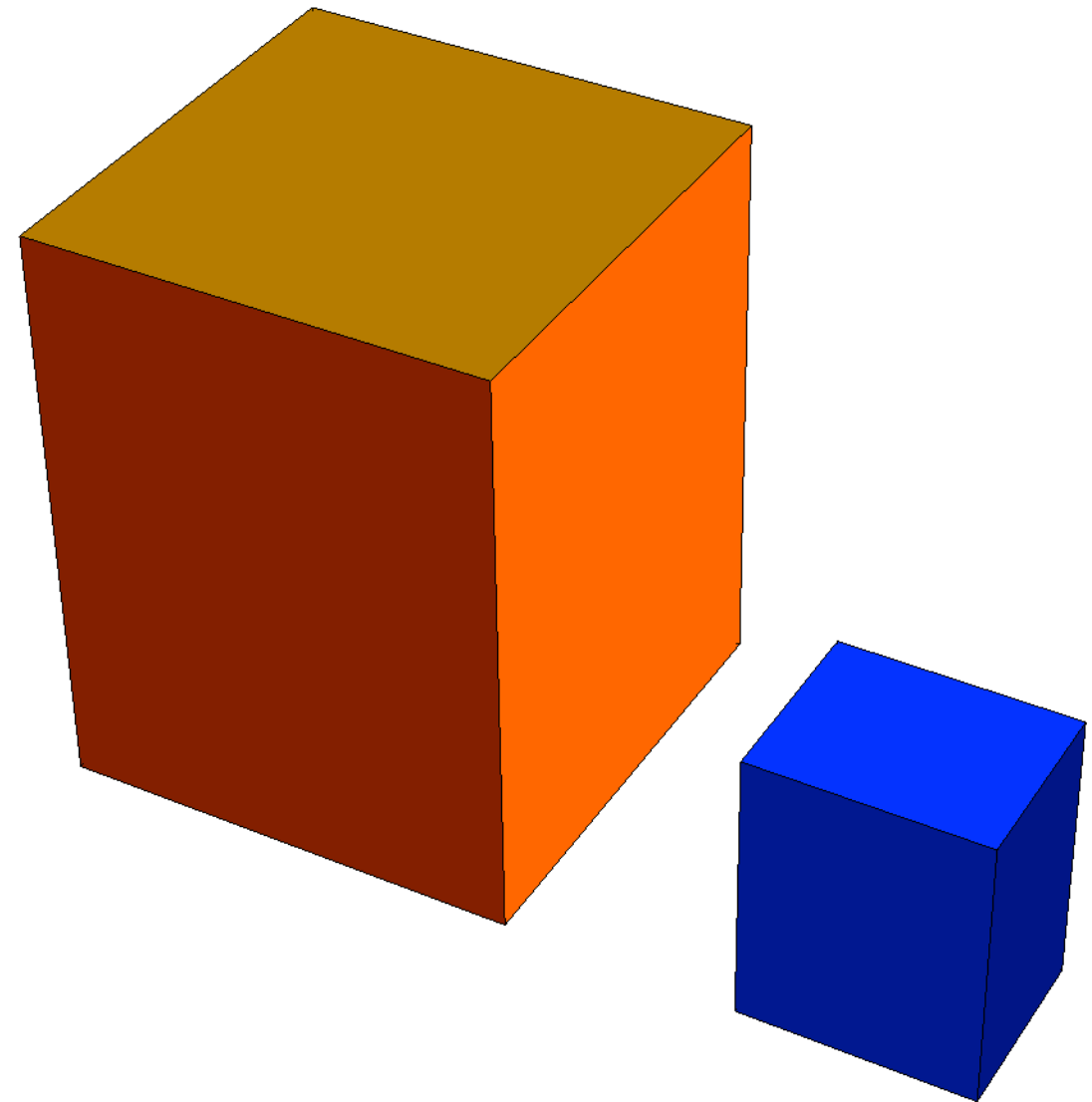
L'Garde Website

# Comparison

## Sunjammer vs. Solar Cube 12 Blade

Sunjammer Stowed  
60cm x 60cm x 76cm  
31 kg

Solar Cube 12 Blade Stowed  
22cm x 24cm x 37cm  
16 kg



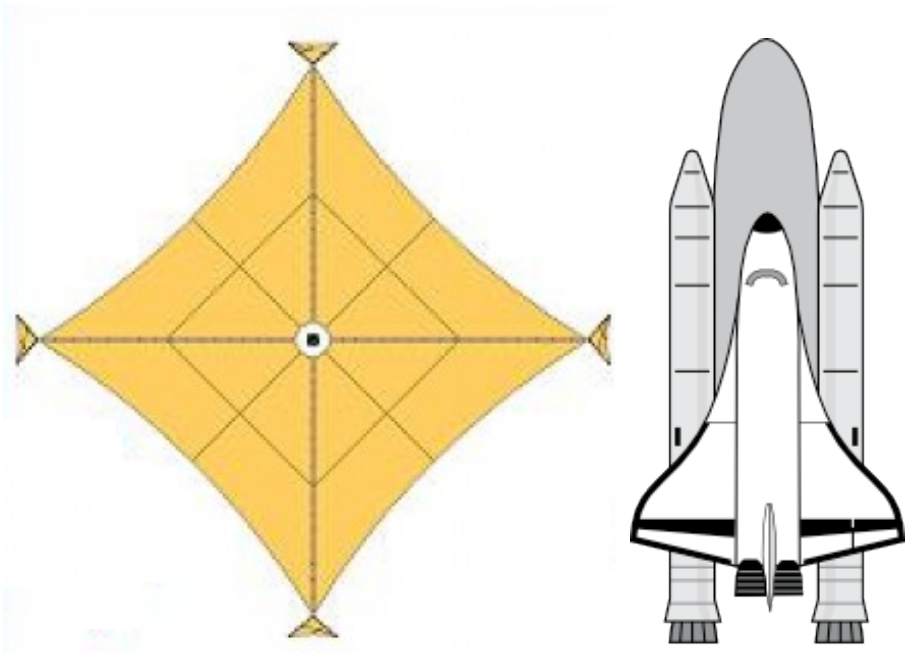
Sunjammer Char.Accel: 0.34 mm/s<sup>2</sup>

Solar Cube 12 Blade Char.Accel: 0.7 mm/s<sup>2</sup>

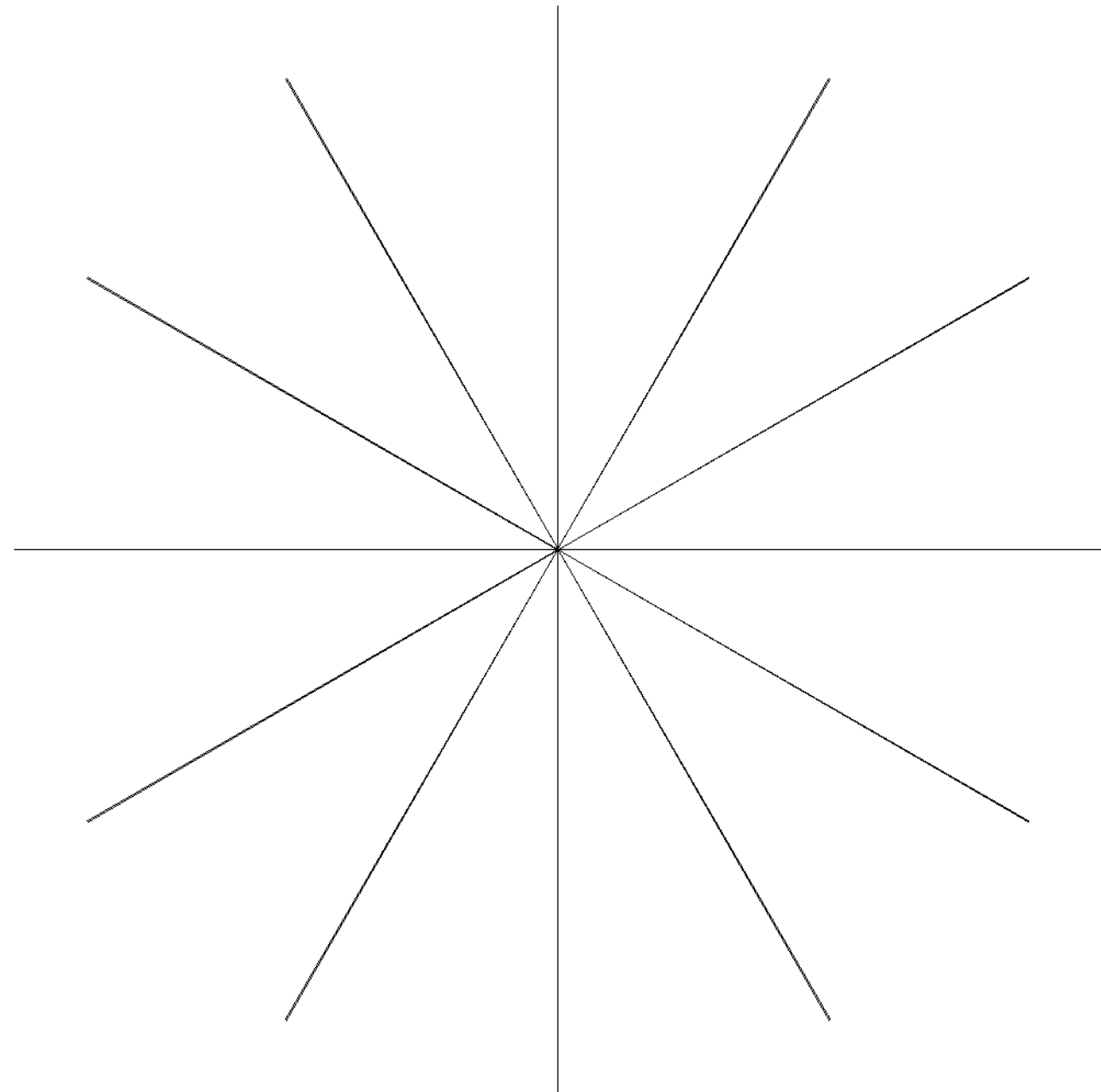


# Comparison

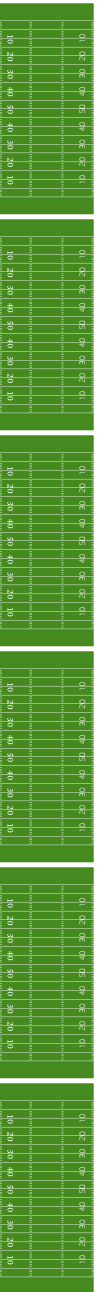
## Sunjammer vs. Solar Cube 12



Sunjammer Deployed  
35m x 35m



Solar Cube 12 Blade Deployed  
640m across



# MacNeal's Spinning Room Test

## Blade Properties

Thickness: .001" (Kapton)

Chord,  $C = 1.938"$

Weight/unit area =  $1.08 \times 10^{-4}$  lb/in<sup>2</sup> (Kapton plus paint)

Modulus of elasticity,  $E = 500,000$  psi

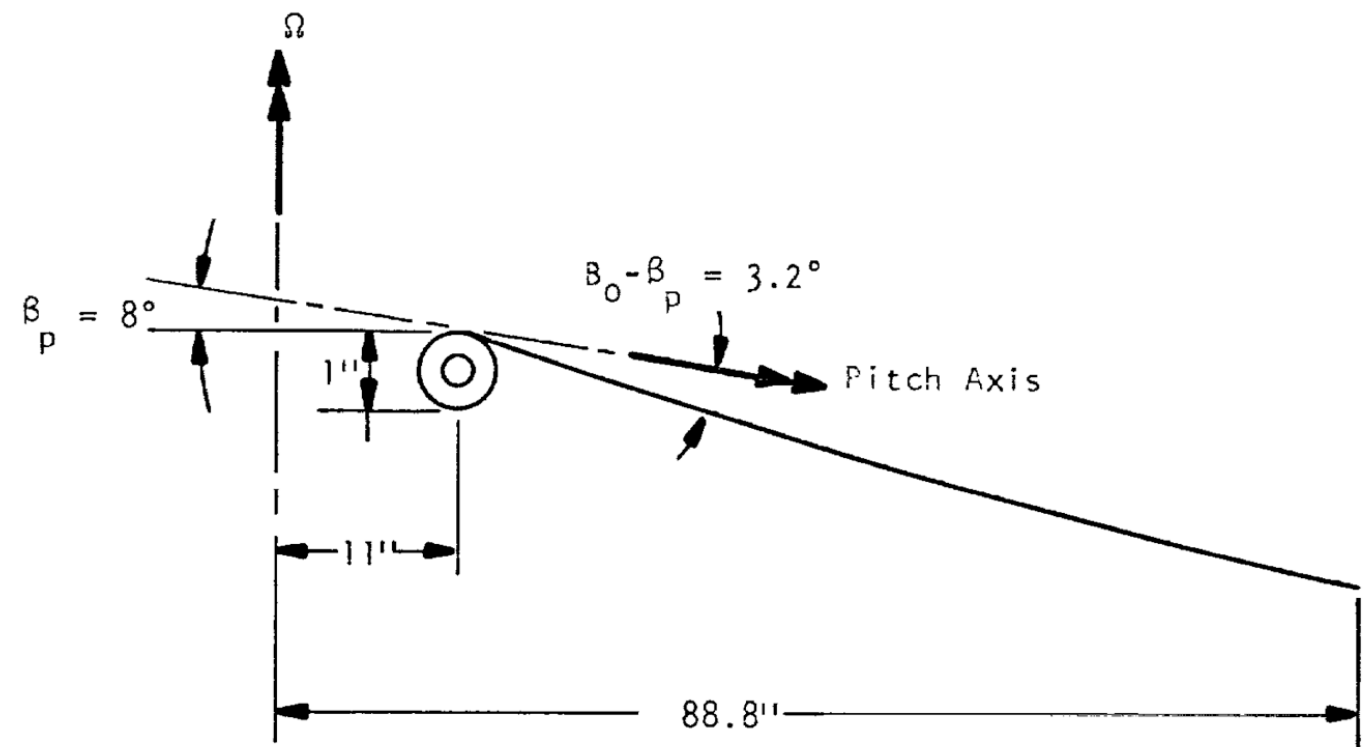
## Operating Parameters

Spin rate,  $\Omega = 2\pi$  rad/sec

Stress at Centerline,  $\sigma_o = 43.6$  psi

Coning angle at tip,  $\beta_t = 6.33^\circ$

Inplane Stiffness Parameter,  $K = \frac{1}{12} \left( \frac{E}{\sigma_o} \right) \left( \frac{C}{R} \right)^2 = .454$

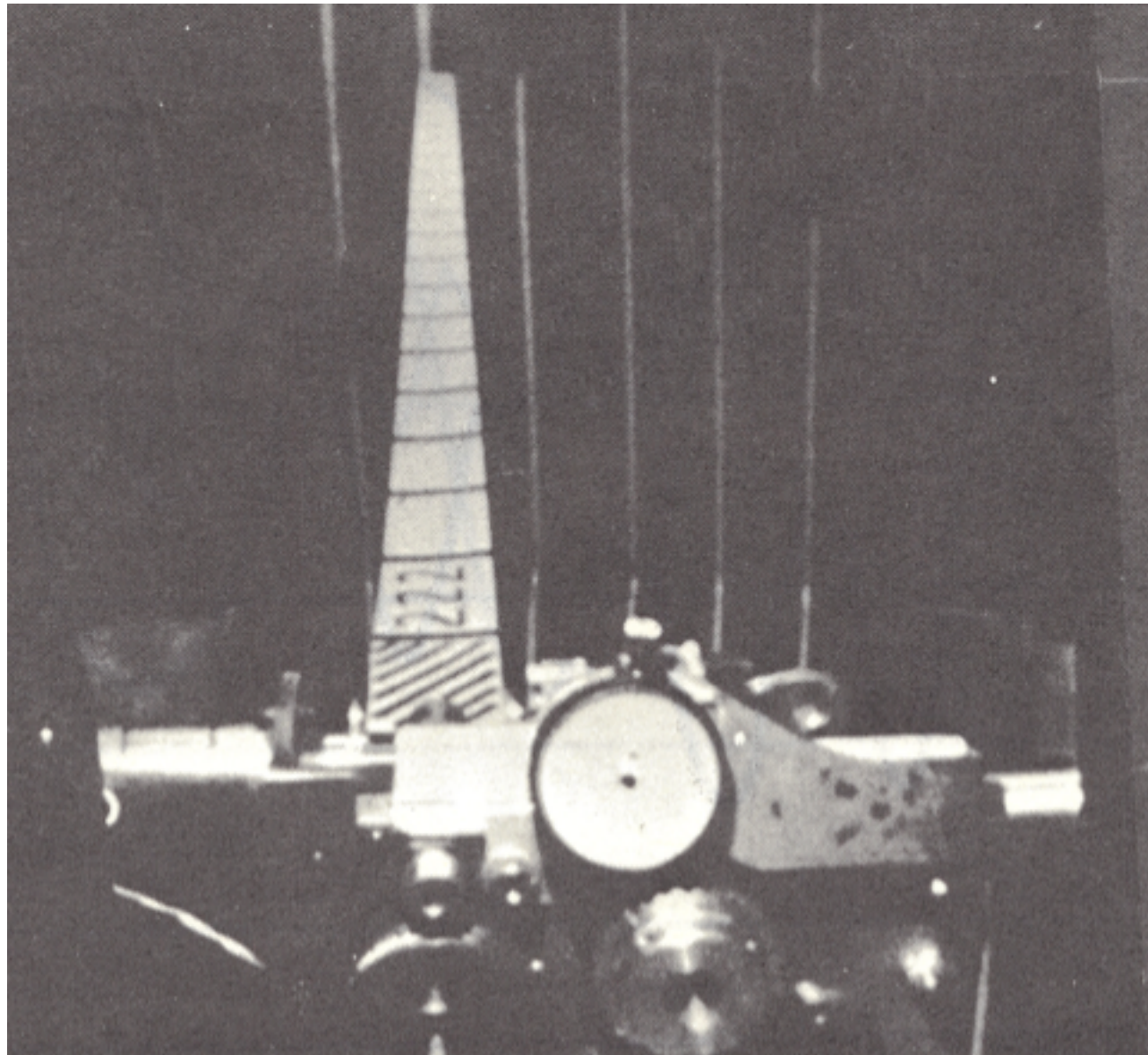


MacNeal, R. H., "Structural Dynamics of the Heliogyro", NASA-CR-1745A, 1971.

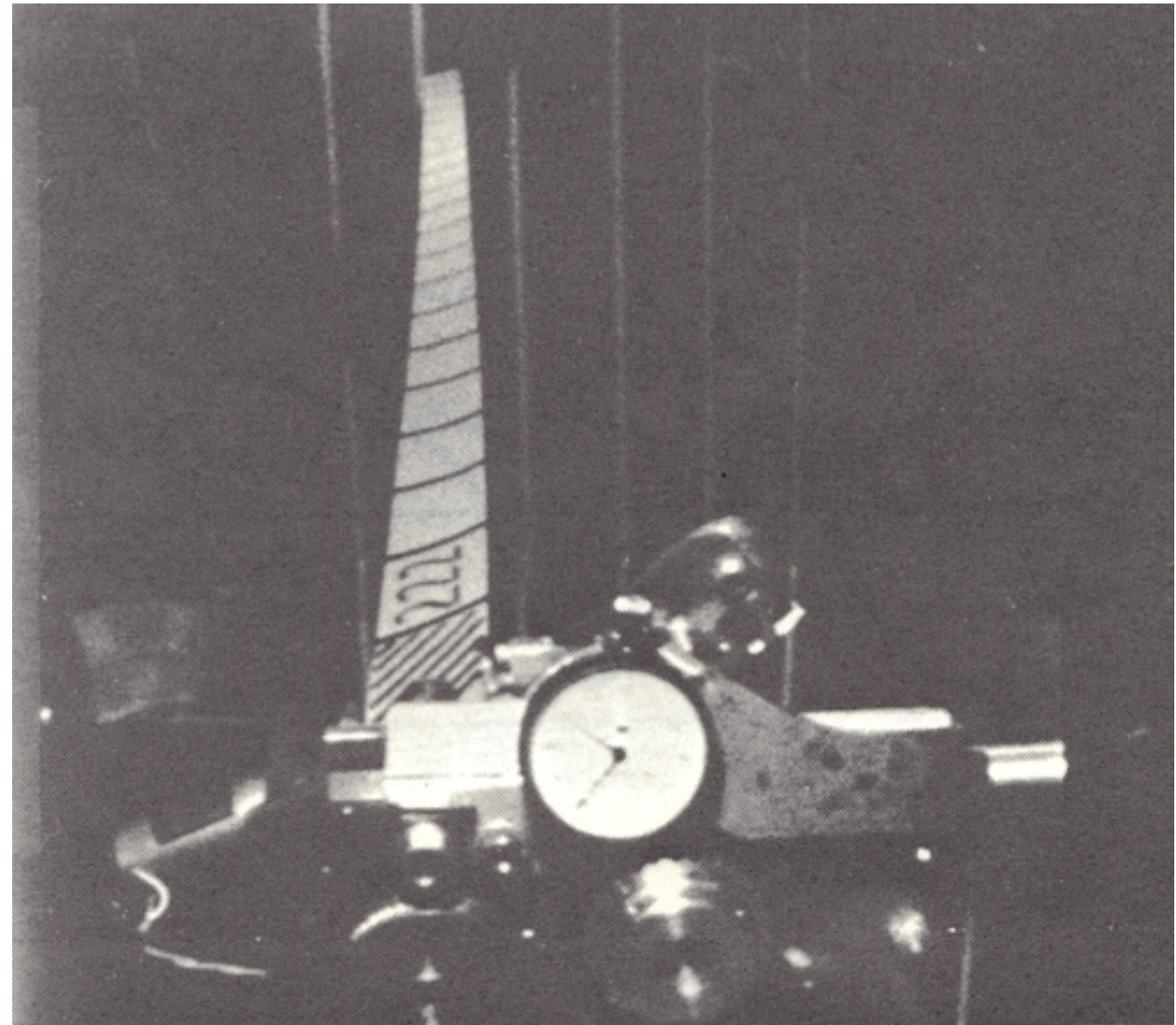
Deploy and pitch a blade in an 18 foot diameter spinning room



# MacNeal's Spinning Room Test



0 Degree Pitch

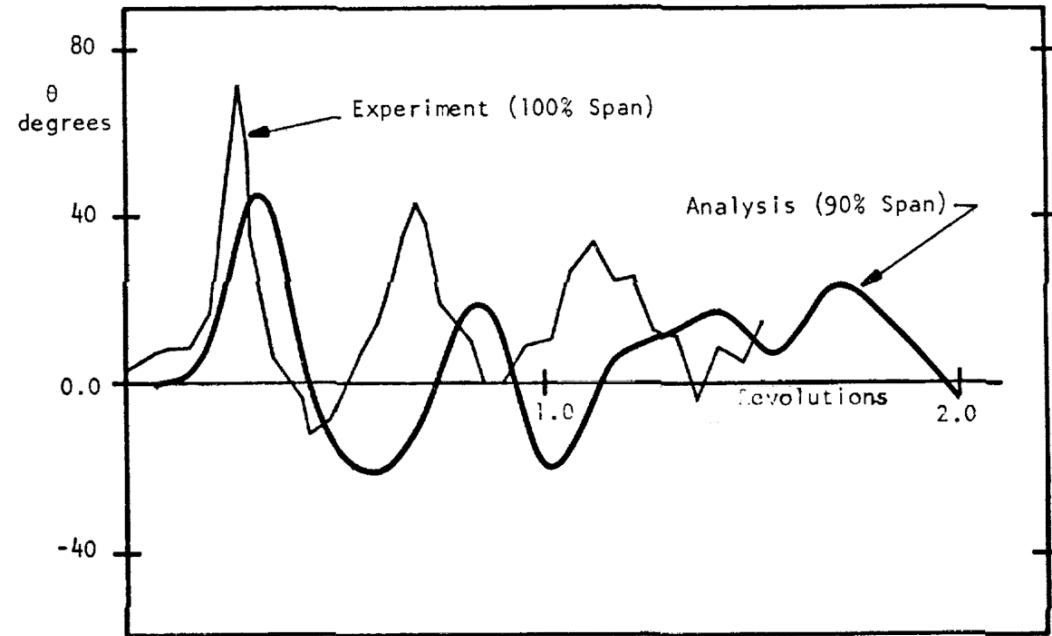


25 Degree Collective Pitch

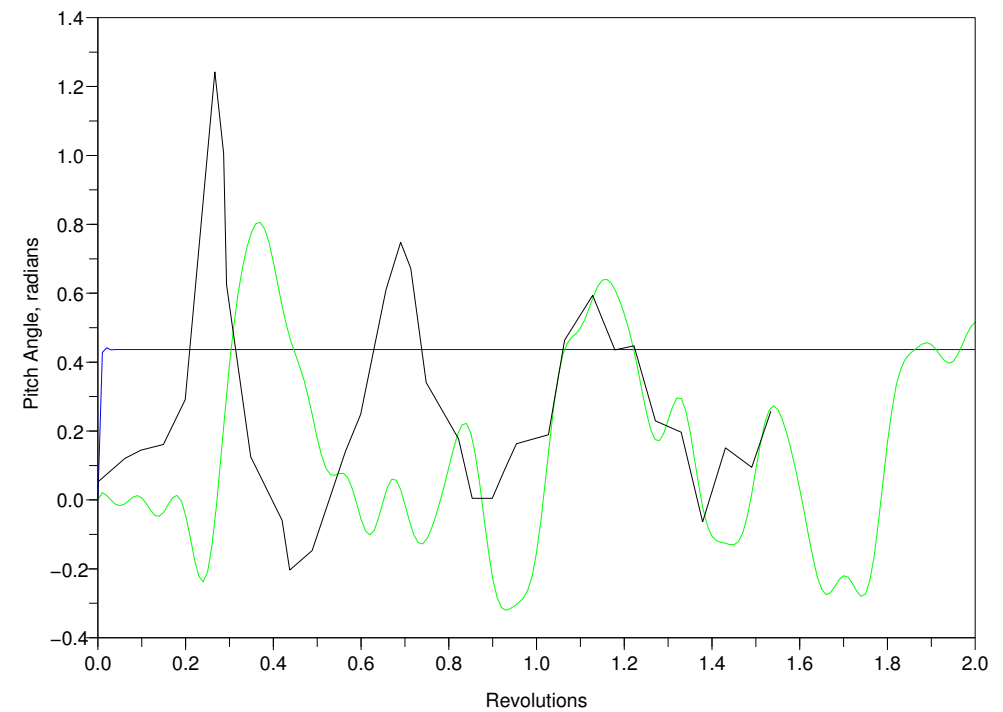
# MacNeal's Spinning Room Test

## Step Increase in Collective Pitch, $0^\circ$ to $25^\circ$ , Calculated Damping

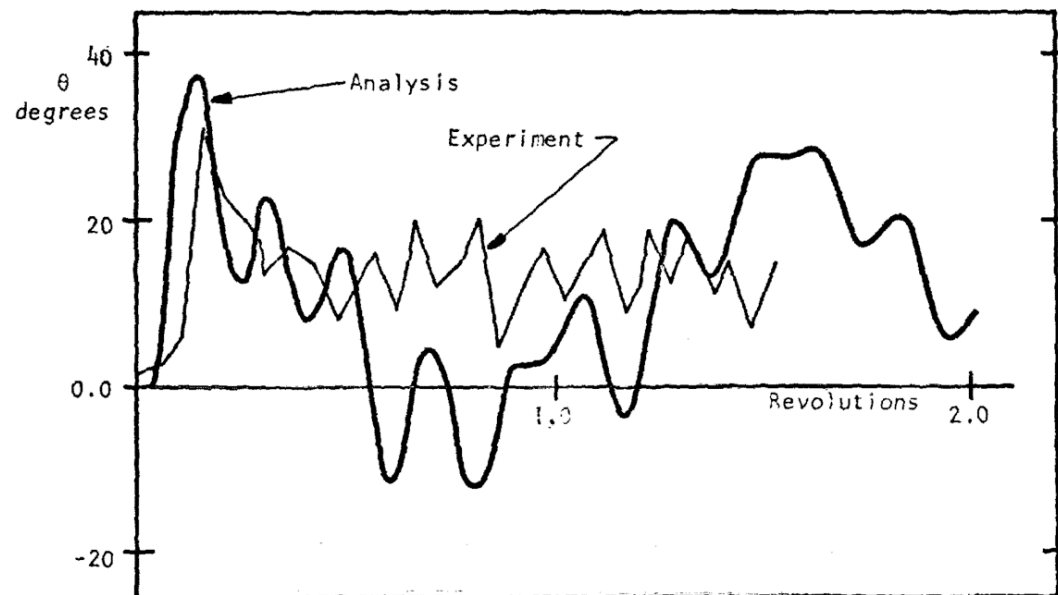
(b) Pitch Angle at Tip



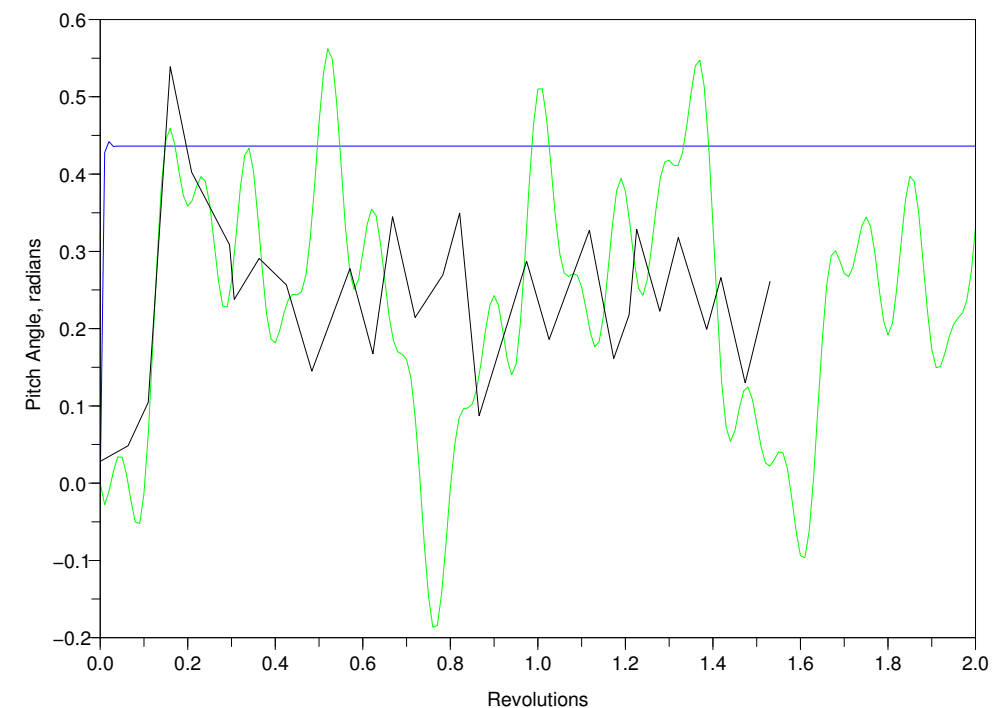
Pitch at tip, fast rise, realistic damping. Green = Analysis; Blade = Experimental; Blue is the Pitch at the Root



(a) Pitch Angle at 50% Span



Pitch, 50% span, fast rise, realistic damping. Green=Analysis; Blade=Experimental; Blue is the Pitch at the Root

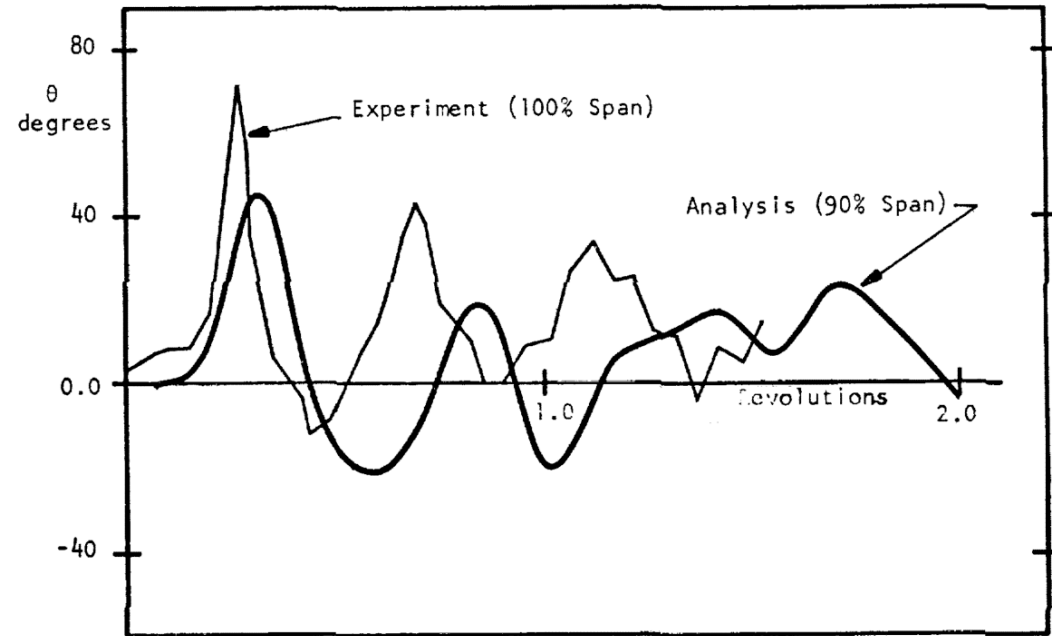




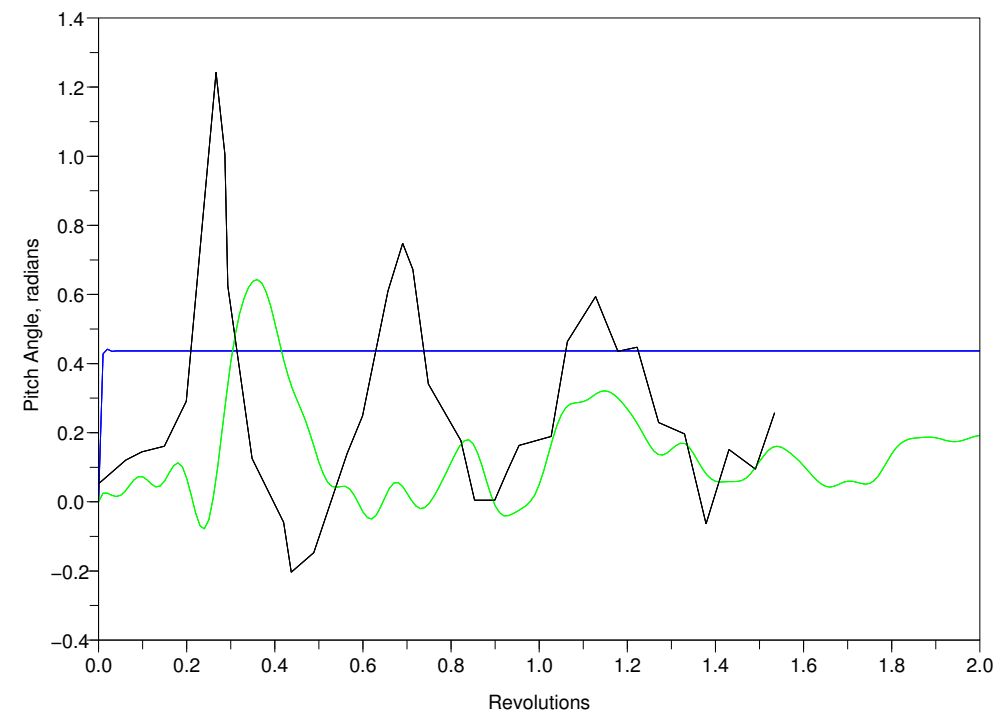
# MacNeal's Spinning Room Test

## Step Increase in Collective Pitch, $0^\circ$ to $25^\circ$ , Increased Damping

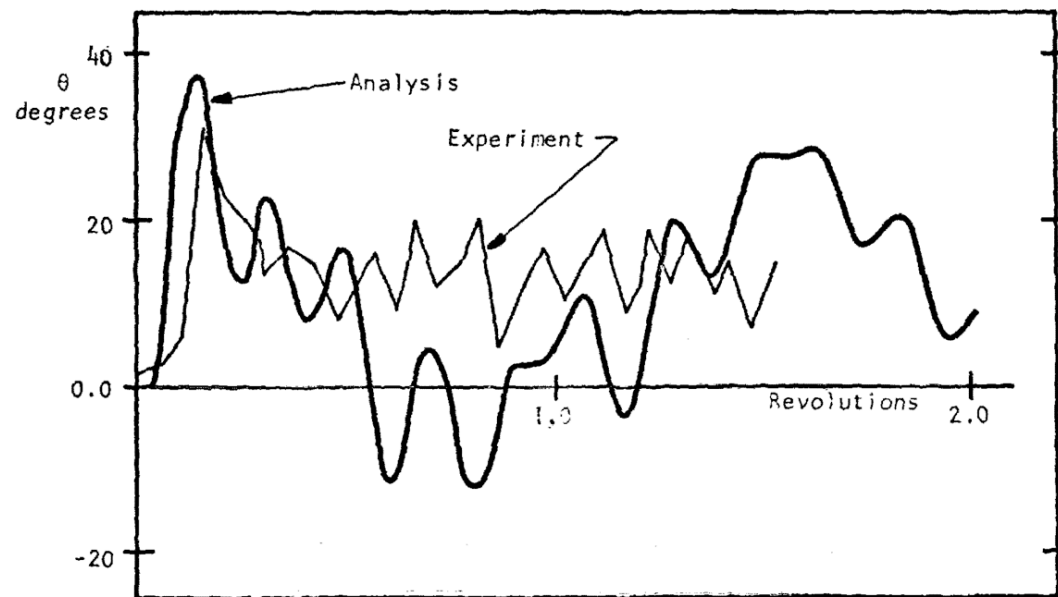
(b) Pitch Angle at Tip



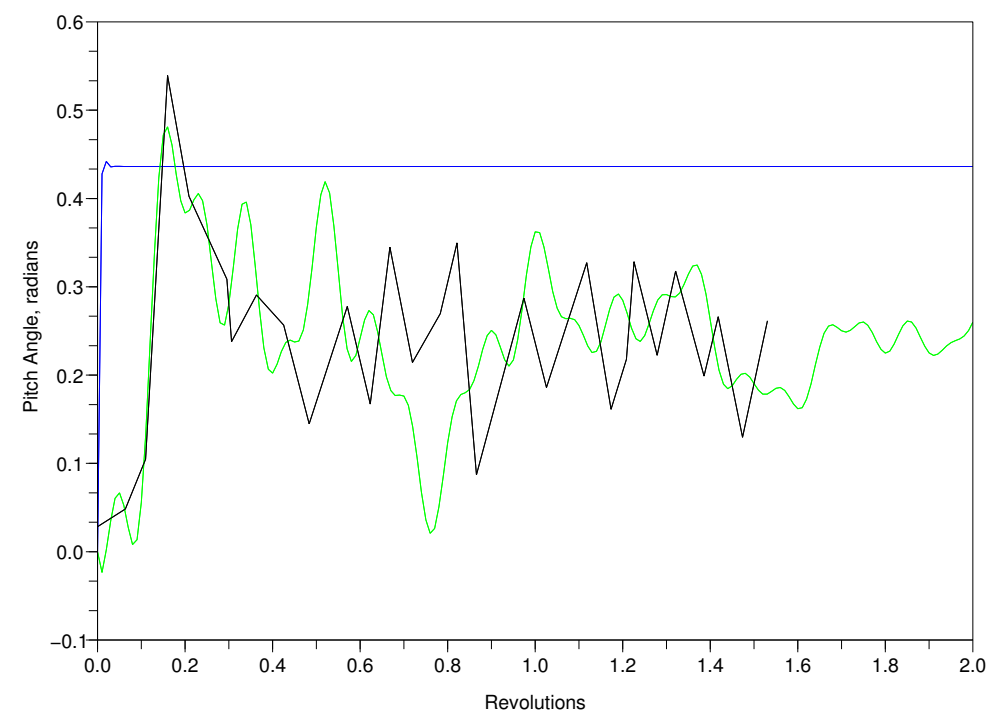
Pitch at tip, fast rise, pitch damping 50x. Green = Analysis; Blade = Experimental; Blue is the Pitch at the Root



(a) Pitch Angle at 50% Span



Pitch, 50% span, fast rise, pitch damping 50x. Green=Analysis; Blade=Experimental; Blue is the Pitch at the Root



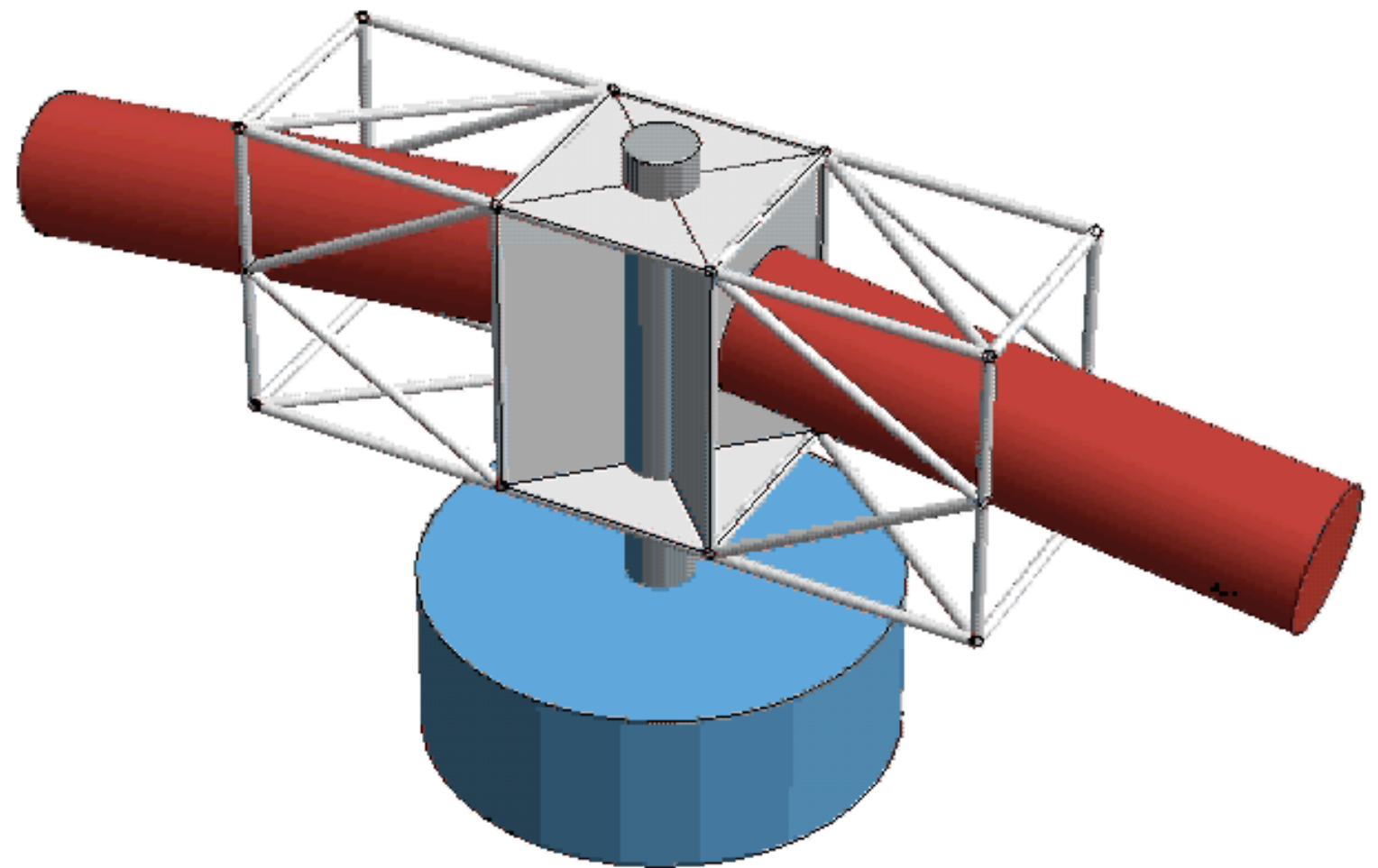
# MacNeal's Spinning Room Test

Step Increase in Collective Pitch,  $0^\circ$  to  $25^\circ$  -- CONCLUSIONS

- MacNeal's Analysis used uncoupled pitch, in-plane, out-of-plane modes.
- Blomquist uses coupled modes
- MacNeal knew the details of the test
- Blomquist is guessing what the test conditions were.
- Getting damping right is essential.
- **THEREFORE, A RETEST TO VERIFY CURRENT MODELS, AS WELL AS ACTUATION AND MODAL DAMPING STRATEGIES, IS NEEDED**

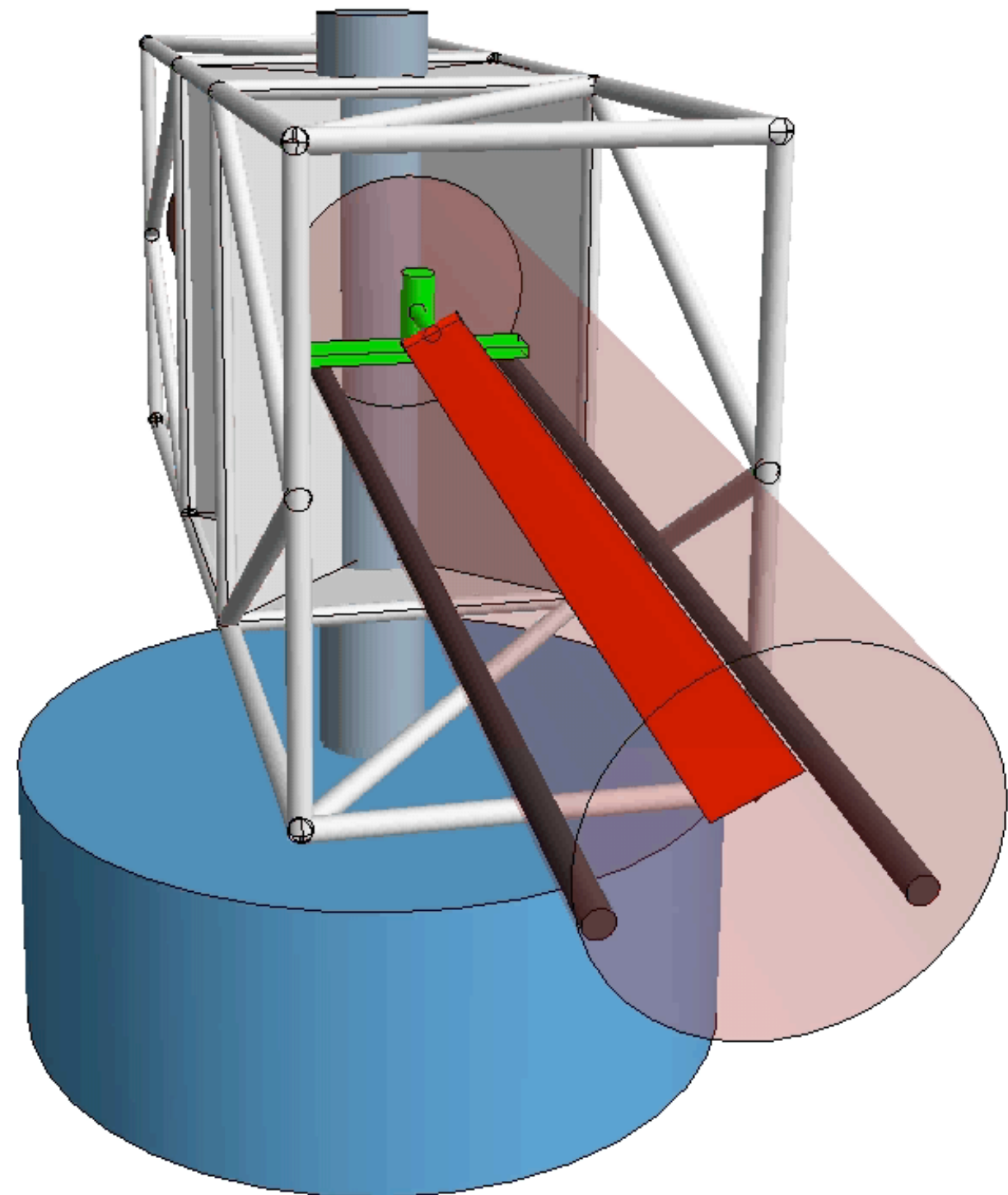
# Centrifuge for spinning blade tests

- 2.5 meter tubes
- Spinning at 60 rpm
- Tubes inclined downward  $7^\circ$
- Cameras inside



# Centrifuge for spinning blade tests

- Blades unfurl as pitch device moves radially inward
- Blades pitch as in MacNeal's test





# CONCLUSION

The Solar Cube Heliogyro Cubesat can open Solar  
System exploration to the masses

Look for things to come...